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import gym
import numpy as np
import random
from stable baselines3 import PPO
import matplotlib
matplotlib.use("TkAgg")
import matplotlib.pyplot as plt
import torch
import torch.nn as nn
episode durations = [] #only used for plotting how long the games are
episode rewards = [] #only used for finding the final rewards of the game
is ipython = 'inline' in matplotlib.get backend()
if is ipython:
plt.ion()
class BSGameEnv(gym.Env):
    def plot rewards(show result=False): #plots the rewards
        plt.figure(1)
        rewards = torch.tensor(episode rewards, dtype=torch.float)
        if show result:
            plt.title('Result')
            plt.clf()
            plt.title('Training...')
       plt.xlabel('Episode')
       plt.ylabel('Episodic Reward')
       plt.plot(rewards.numpy())
        if len(rewards) \geq 5:
            plt.plot(means.numpy())
        plt.pause(0.001) # pause a bit so that plots are updated
        if is ipython:
            if not show result:
                display.display(plt.gcf())
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display.clear output(wait=True)
            display.display(plt.gcf())
def plot durations (show result=False): #plots how long the games are
   plt.figure(2)
    durations t = torch.tensor(episode durations, dtype=torch.float)
    if show result:
        plt.title('Result')
        plt.clf()
        plt.title('Training...')
    plt.xlabel('Episode')
   plt.ylabel('Duration')
   plt.plot(durations t.numpy())
    if len(durations t) \geq 5:
        means = durations t.unfold(0, 100, 1).mean(1).view(-1)
        plt.plot(means.numpy())
    plt.pause(0.001) # pause a bit so that plots are updated
    if is ipython:
        if not show result:
            display.display(plt.gcf())
            display.clear output(wait=True)
            display.display(plt.gcf())
def addCards(self, player, gamecards): #adds two card piles together
    newState = [a + b for a, b in zip(player, gamecards)] #adds the
    return newState
def findTheStateOfTheGame(self, playerCards):
    print("player cards", playerCards)
    stateOfTheGame = [0] * 13 # makes a blank list with 0's
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for card in playerCards:

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stateOfTheGame[card] += 1 # adds a value for the cards (0-12
       return stateOfTheGame
   def resetDuplicate(self):
       self.cardsInTheGame = []
       self.pastPutdown = [1,0,0] #just sets the past put down to nothing
       self.numberOfCards = random.randint(30, 45) #finds a random amount
       self.cards in game = [2, 2, 2, 2, 3, 3, 3, 3, 4, 4, 4, 4, 5, 5, 5,
5, 6, 6, 6, 6, 7, 7, 7, 7, 8, 8, 8, 8, 9, 9, 9, 9,
                  self.cardsInTheGame = random.sample(self.cards in game,
self.numberOfCards) #samples the numbers 30-45
       if len(self.cardsInTheGame) % 2: #so that there is an even number
          self.cardsInTheGame.pop()
       self.stateOfPlayer1 = random.sample(self.cardsInTheGame,
len(self.cardsInTheGame) // 2) #finds player 1 state by sampling half the
       self.stateOfPlayer1 =
self.cardsInTheGame =
self.findTheStateOfTheGame(self.cardsInTheGame) #reorganizes the total
       self.stateOfPlayer2 = [abs(a - b) for a, b in]
zip(self.cardsInTheGame, self.stateOfPlayer1)] #subtracts player 1 from
       self.stateOfTheGame = np.zeros(13, dtype=np.int32) #makes the
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self.number for player1 = self.numberOfCards // 2 #assigns the
        self.number for player2 = self.numberOfCards // 2
        self.action space = gym.spaces.MultiDiscrete((3, 13, 4, 3, 14, 4,
3, 13, 4, 3, 13, 4)) #assigns the action space, 3(bs, nothing, action)
much is in the stack, and the current cars it's on
        self.fixednumber for player1 = [self.number for player1] #
Initialize as a list of 13 zeros
       self.observation space = gym.spaces.Dict({
            'player1 count': gym.spaces.Box(low=0,
high=self.numberOfCards, shape=(13,), dtype=np.int32),
            'player1 cards': gym.spaces.Box(low=0,
high=self.numberOfCards, shape=(1,), dtype=np.int32),
            'player2 count': gym.spaces.Box(low=0,
high=self.numberOfCards, shape=(1,), dtype=np.int32),
            'stack count': gym.spaces.Box(low=0, high=self.numberOfCards,
shape=(1,), dtype=np.int32),
            'current card': gym.spaces.Box(low=0, high=13, shape=(1,),
dtype=np.int32) #the position of the current card
        self.stepsDone = 0 #sets the steps done to 0
        self.reward = 0 #makes the reward 0
       self.pastBSTrue = False #makes a global variable to check if bs
   def init (self):
        self.resetDuplicate()
   def bs(self, player_state, current_card, past put down):
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for i in range(len(past put down) - 1): #looks at what was put
down
           if past put down[i] %3 == 2: #if it's an action card
               if past put down[i % 3 + 1] != index value: # If any
                    bs true = True # Set BS to false
       player state = self.addCards(player state, self.stateOfTheGame)
       if bs true:
           return True, player state
           return False, player state
   def step(self, action):
       self.stepsDone += 1
       bs call, action string = self.translate actions to string(action)
       if (bs call ):
           number cards put down = 0 #no cards are put down since the
           addCards = sum(self.stateOfTheGame) #find the total amount of
           BS DECISION, playerState = self.bs(self.stateOfPlayer1,
(self.stepsDone -1) % 13, self.pastPutdown) #finds out who told the truth
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self.reward -=0.03
                self.stateOfPlayer1 = playerState #the agent takes the
                self.number for player1 += addCards #the agent get's all
                self.stateOfTheGame = [0,0,0,0,0,0,0,0,0,0,0,0,0] #the
game is set to Os
                order card = np.zeros(13, dtype=np.int32)
                order card[self.stepsDone % 13] = 1 # Set the current
                order card = [self.stepsDone %13 -1]
                observation = {
                    'player1 count': self.stateOfPlayer1.copy(),
                    'player1 cards': [self.number for player1].copy(),
                    'player2 count': [self.number for player2].copy(),
                    'stack count': [len(self.stateOfTheGame)].copy(),
                    'current card': order card.copy() # Use an array to
                done = (self.number for player1 <= 0) or</pre>
(self.number for player2 <= 0) or self.stepsDone > 1000
                reward = self.get reward(done)
                self.stateOfTheGame = [0,0,0,0,0,0,0,0,0,0,0,0,0]
                return observation, reward, done, {} #restarts, since obvv
                self.reward +=0.03
                self.stateOfPlayer2 = self.addCards(self.stateOfPlayer2,
self.stateOfTheGame) #player 2 takes the cards
                self.number for player2 += addCards #player 2 gets more
                self.stateOfTheGame = [0,0,0,0,0,0,0,0,0,0,0,0,0]
            actual action string = []
            number cards put down = 0
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for i in range(len(action string)-2): # Loop through the
action string with step size 3
                if i%3 == 2: # If action is to put down cards
                    type_of_card = action string[i + 1] #everything
shifted back
                   number of card = action string[i + 2]
                    if self.stateOfPlayer1[type of card-1] >=
number of card: # Check if player has enough cards
                        self.stateOfPlayer1[type of card-1] -=
number of card #if it does subtract
                        self.stateOfTheGame[type of card-1] +=
number of card #add to the card stack
                        self.number for player1 -= number of card
                        number cards put down += number of card #records
how many cards were put down
                        if(number cards put down>4):
                        actual action string.append(2) #ritten out that it
                        actual action string.append(type of card)
                        actual action string.append(number of card)
       self.stepsDone +=1 #the agent has taken it's turn!!
       BS DECISION = False
automatically bs !
       if (bs_call == True) or (number_cards_put_down ==0):
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BS DECISION, stateOfPlayer = self.bs(self.stateOfPlayer2,
(self.stepsDone - 1) % 13, actual action string) #figures out if the agent
            addCards = sum(self.stateOfTheGame)
                self.reward -=0.03 #if the agent lied :((
                self.stateOfPlayer1 = self.addCards(self.stateOfPlayer1,
self.stateOfTheGame) #player 1 takes the cards
                self.number for player1 += addCards
                self.stateOfTheGame = np.zeros(13, dtype=np.int32)
                self.reward +=0.03
                self.stateOfPlayer2 = stateOfPlayer
                self.number for player2 += addCards
                self.stateOfTheGame = np.zeros(13, dtype=np.int32)
            self.pastPutdown = [0,0,0] #0 = bs, and 0 cards and 0 amount
            positions of i = (self.stepsDone-1) % 13
            number of cards = self.stateOfPlayer2[positions of i] #finds
put down)
           randomNumber = 0
            if number of cards > 0:
                    randomNumber = random.randint(1, number of cards)
                number of cards = 0 #sets it to 0 and finds a spot that
does nottt have 0 cards
                while number of cards<=0: #hile something has 0 cards</pre>
                    positions of i = (positions of i +1)% 13
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number of cards = self.stateOfPlayer2[positions of i]
                if number of cards >0: #once it breaks the past loop
                    randomNumber = random.randint(1, number of cards)
                    randomNumber = 0
            self.stateOfPlayer2[positions of i]-= randomNumber #subtracts
           self.stateOfTheGame[positions of i] += randomNumber
            self.number for player2 -= randomNumber
            self.pastPutdown = [2, positions of i, randomNumber] #writes
down the move it took
       order card = np.zeros(13, dtype=np.int32)
        order card = [self.stepsDone % 13-1] # Set the current card
       observation = {
            'player1 count': self.stateOfPlayer1.copy(),
            'player1 cards': [self.number for player1].copy(),
            'player2 count': [self.number for player2].copy(),
            'stack count': [len(self.stateOfTheGame)].copy(),
            'current card': order card.copy() # Use an array to represent
       done = (self.number for player1 <= 0 ) or (self.number for player2</pre>
<= 0 ) or self.stepsDone > 1000
       if done:
            print("number for player 1:", self.number for player1)
            print("number for player 2:", self.number for player2)
            print("steps done:", self.stepsDone)
        reward = self.get reward(done)
        return observation, reward, done, {}
   def get reward(self, done):
       if done:
            print("player 1 state:", self.stateOfPlayer1)
            print("player 2 state:", self.stateOfPlayer2)
            print("state of the game:", self.stateOfTheGame)
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if self.number for player1 <= 0:
                self.reward += 5
           elif self.number for player2 <= 0:</pre>
               self.reward-= 5
               if (self.number_for_player1+3)<self.number_for_player2:</pre>
                    self.reward += 1.0
                    self.reward-= 1.0
           episode durations.append(self.stepsDone)
           episode rewards.append(self.reward)
           print("player 1 number", self.number for player1, "player 2
number", self.number for player2)
           return self.reward
       self.resetDuplicate()
       order card = np.zeros(13, dtype=np.int32)
       order card[self.stepsDone % 13] = 1 # Set the current card
       order card = [self.stepsDone%13 -1]
       observation = {
            'player1 count': self.stateOfPlayer1.copy(),
            'player1 cards': [self.number for player1].copy(),
            'player2 count': [self.number for player2].copy(),
            'stack count': [len(self.stateOfTheGame)].copy(),
            'current card': order card.copy() # Use an array to represent
       return observation
   def render(self, mode='human'): #doesn't matter just prints if wanted
       print("Number of cards for player 1:", self.number for player1)
       print("Number of cards for player 2:", self.number for player2)
```

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def close(self): #sorta needed for the structure
def translate actions to string(self, action):
   bs call = False
   action string = []
   positions of bs = self.pastBSTrue #if there was a bs previously
    if (positions of bs == True): #the agent can't put down bs
        bs call = False
        for i in range(len(action)):
                if action[i] == 0: #0 means it's bs
                elif action[i] == 1: #1 means no action
                    action string.append(1)
                elif action[i] == 2: #2 means to take an action
                    action string.append(2)
                action string.append( action[i]) # appends the number
            elif i % 3 == 2:
                action string.append( action[i]) #appends the number
        for i in range(len(action)):
                if action[i] == 0:
                    action string.append(0)
                elif action[i] == 1:
                    action string.append(1)
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```
action string.append(2)
                    action string.append( action[i])
                    action string.append( action[i])
        return bs call, action string
env = BSGameEnv()
model = PPO('MultiInputPolicy', env, verbose=1)
model.load("Final Test5")
model.learn(total timesteps=int(2e6))
model.save("Final Test7") # Saves the final policy
for i in range(1):
   obs = env.reset()
   score = 0
    ep len mean = []
        action, _ = model.predict(obs)
        obs, rew, term, _ = env.step(action)
       score += rew
            ep len mean.append(env.stepsDone)
            print("IT IS DONE!!!!")
env.plot durations()
env.plot rewards()
plt.ioff()
plt.show() #shows the average rewards and durations
env.close()
```